



# LT01

## User manual

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## Declaration

The contents of this manual might be updated without prior notice; the updated content will be added to the new version of this manual.

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# Contents

<b>1. Product features</b>	4
<b>2. Technical Specification</b>	5
<b>3. Functions</b>	6
3.1 【Basic function-Position】	6
3.1.1 Position and monitoring	6
3.1.2 Timely monitoring	7
3.1.3 Blind zone compensation	6
3.1.4 Cornering Compensation	7
3.1.5 LBS Position	7
3.1.6 AGPS	7
3.2 【Basic function-Alarm function】	7
3.2.1 Low Voltage Alarm	7
3.2.2 Over speed, low speed alarm	8
3.2.3 Vibration alarm	8
3.2.4 Movement alarm	8
3.2.5 GPS error alarm	8
3.3 【Basic function-Intelligent function】	9
3.3.1 Intelligent Power Save	9
3.3.2 Intelligent Self-diagnosis	9
3.3.3 Static Drift Suppression	8
3.3.4 Mileage Statistics	8
3.3.5 Remote Configuration	10
3.3.6 Remote Upgrade (OTA)	10
3.3.7 Dual IP or Domain	9
3.3.8 JTT808 protocol	9
<b>4. Installation guide</b>	11
4.1 Installation Diagram	错误！未定义书签。
4.2 Installation and debugging process	错误！未定义书签。
4.2.1 SIM install	11
4.2.2 Main unit power on	11
4.2.3 Recommended Installation place	12
4.2.4 Parameter setting by SMS	11

## PART 01 Product Overview



- Support GPS/Beidou, AGPS, LBS, with accurate position performance;
  - Built in high sensitive G-sensor accelerometer
  - Supports intelligent self-diagnosis, intelligent power save mode, remote fuel and power cut off, OTA and alarm functions
  - Small in size and wide voltage, especially designed for scooter, motorcycle, electric vehicles and automotive financial risk control project
- Small and convenient for conceal installation

## PART 02 Technical Specification

Characteristics	Description
Working Voltage	DC 9V-36V, applicable to 12V/24V vehicles
	DC 9V-100V, applicable to scooter, motorcycle and electric vehicles management
Working current	Average current < 30mA (DC12V), Maximum current < 100mA (DC12V) Sleep current < 10mA
Built in battery	110mAh, 3.2V, Lithium polymer battery
Battery protection	Anti-200V power supply reverse connection; main voltage detection;;
Dimension	88mm*45mm*14mm (L*W*H)
Weight	47 ± 5g
Memory	1300 pcs of data storage
Working Temperature	-20°C ~ 70°C
Storage Temperature	-40°C ~ 85°C
Relative humidity	5% ~ 95%

Frequency	<p>Standard cat1 version:            LTE FDD: Band 1/3/5/8            LTE TDD: Band 34/38/39/40/41            GSM: 900/1800MHz</p> <p>Cat1-EU version:            LTE FDD: B1 B3 B7 B8 B20 B28            GSM: 900/1800MHz</p>
GNSS Parameters	<p>GPS L1:1575.42MHz;            BD B1: 1561.098MHz</p>

## PART 03 Functions

### 3.1 Basic function-Tracking function

Including timely upload, blind zone compensation, speed mileage statistics, area monitoring and other functions, the backend sends positioning commands, and the terminal uploads data including longitude, latitude, speed, direction, and status information.

#### 3.1.1 Timely Tracking

The device can be set to upload the position and status information of the vehicle to the backend at a certain time or a certain period or at a certain time interval.

### **3.1.2 Blind area data storage**

When the vehicles enters the GPRS blind area, the device will store the GPS data upon 15s interval, the track data will be saved at the shortest 15S interval, those data will be uploaded to the backend server once GPRS network recovered, minimum 1000 pcs of data can be stored.

### **3.1.3 Cornering Compensation**

If the device detects that the vehicle driving direction has certain angular deviation(default 15 degrees), the device will upload a packet extra to make sure the driving trace is more accurate.

### **3.1.4 LBS**

If GPS is not available, the device will automatically switch to LBS mode, and acquire the LBS each 30s and upload the based information, the server shall interprets the specific location on the map.

### **3.1.5 AGPS**

The device supports AGPS, once the device is connected to GPRS, the AGPS can be used to speed up the positioning and improve accuracy.

## **3.2 【Basic function-Alarm function】**

### **3.2.1 Low Voltage Alarm**

When the battery voltage on the vehicle is too low (0-11V or 19-22V), device will report a low voltage alarm to the backend

### **3.2.2 Speeding, low speed alarm**

When the vehicle speed is higher than the preset alarm value, the device will notify the backend. Similarly, when the vehicle speed is lower than preset alarm value, a low speed alarm will be uploaded to the backend, this value is configurable.

### **3.2.3 Vibration alarm**

The device supports vibration alarm, 10 minutes after the ignition off (Arm range 1-20 minutes), the device generates vibration (Delay range 1-10 mins) without ACC connected, the device will upload vibration alarm.

### **3.2.4 Towing alarm**

An alarm is generated when the device is set to a displacement of more than 100 meters (message mode prompt), and the alarm information is reported when the displacement radius exceeds 100 meters when the device is turned off. (Note: displacement range 100~2000m)

The device will send SMS if the vehicle is moved in ignition off status, if the radius is more than 100 meters, will upload towing alarm (Towing range:100-2000m)

### **3.2.5 GPS error alarm**

When the terminal detects that the GPS/BD module is working abnormally, it reports the GPS receiver failure alarm to the backend



## **3.3 【Basic function-Intelligent function】**

### **3.3.1 Power Save**

The device has a built-in high-sensitivity G-sensor accelerometer that monitors the vehicle for motion in real time. When no motion is detected for a long time, the terminal automatically enters the power saving state, meanwhile turns off the GPS/BD module, and GSM enters the heartbeat return mode. In this state, the power consumption of the device is extremely low, which can save power consumption from the vehicle battery.

### **3.3.2 Self-Diagnosis**

The device can perform self-diagnosis. In case there is malfunction regarding GPS and GSM, it will report error message to the backend .The backend can query the current model, version, configuration, running status, and device functions.

### **3.3.3 Static Drift Suppression**

The device has a built-in high-sensitivity G-sensor accelerometer and a complete positioning data-filtering algorithm that filters out most of the static drift data to ensure the accuracy of GPS data.

### **3.3.4 Mileage Calculation**

Mileage data is calculated based on the speed from GPS, The vehicle mileage data is uploaded to the backend along with the vehicle positioning data; the initial mileage can be configured when initially the device is set up.

### **3.3.5 Remote Configuration**

To remote set device parameters including IP, center number and various of monitoring parameters via the backend or SMS.

### **3.3.6 Remote Upgrade (OTA)**

As long as GPRS is connected, remote firmware upgrade can be done remotely

### **3.3.7 Dual IP or Domain**

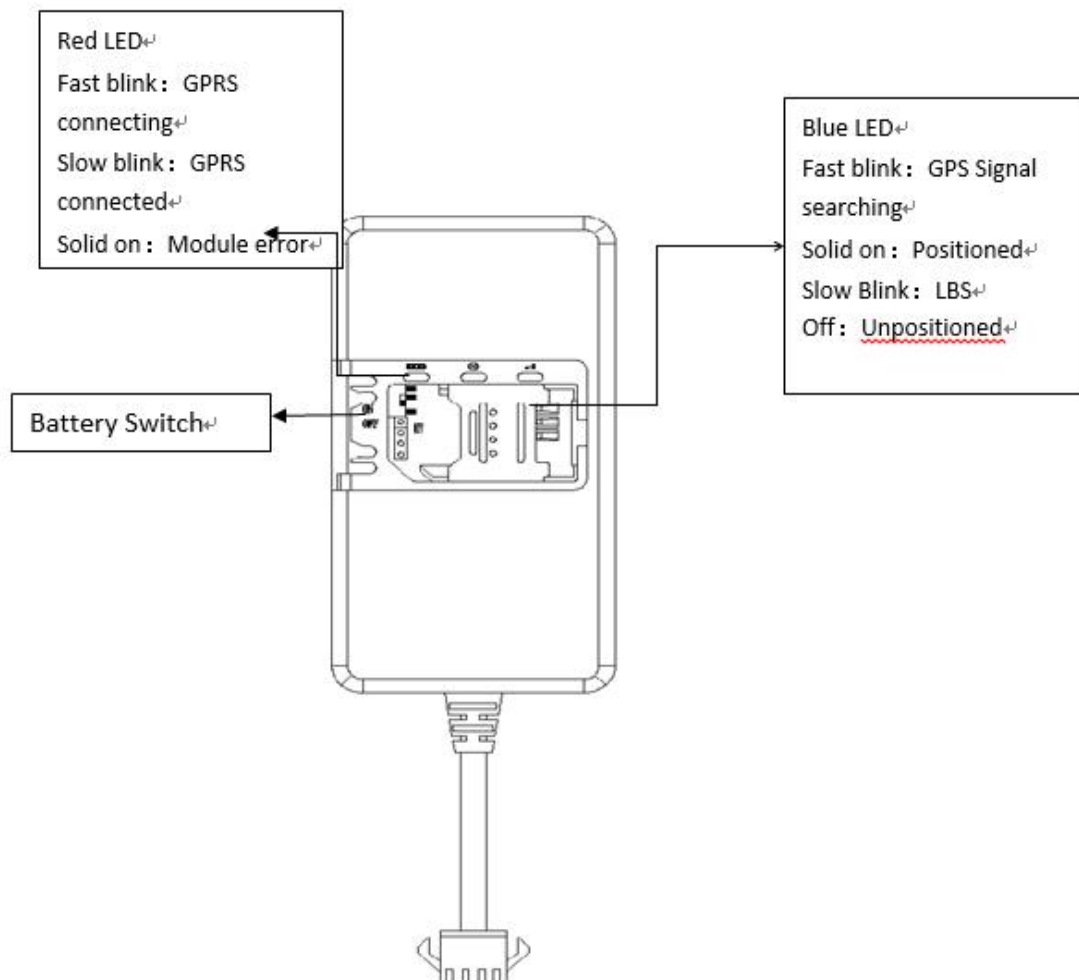
The device supports dual IP connection between the primary server and the standby server. The default connection is the primary server. If there is a problem with the primary server, the device automatically switches to the standby server. The primary server and the standby server can be set in either IP or domain name.

### **3.3.8 JTT808 protocol**

This is government protocol in China, it supports connection to any platform that support JTT808 protocol

## PART 04 Installation guide

### 4.1 Installation Diagram



## 4.2 Installation and debugging process

### 4.2.1 SIM installation

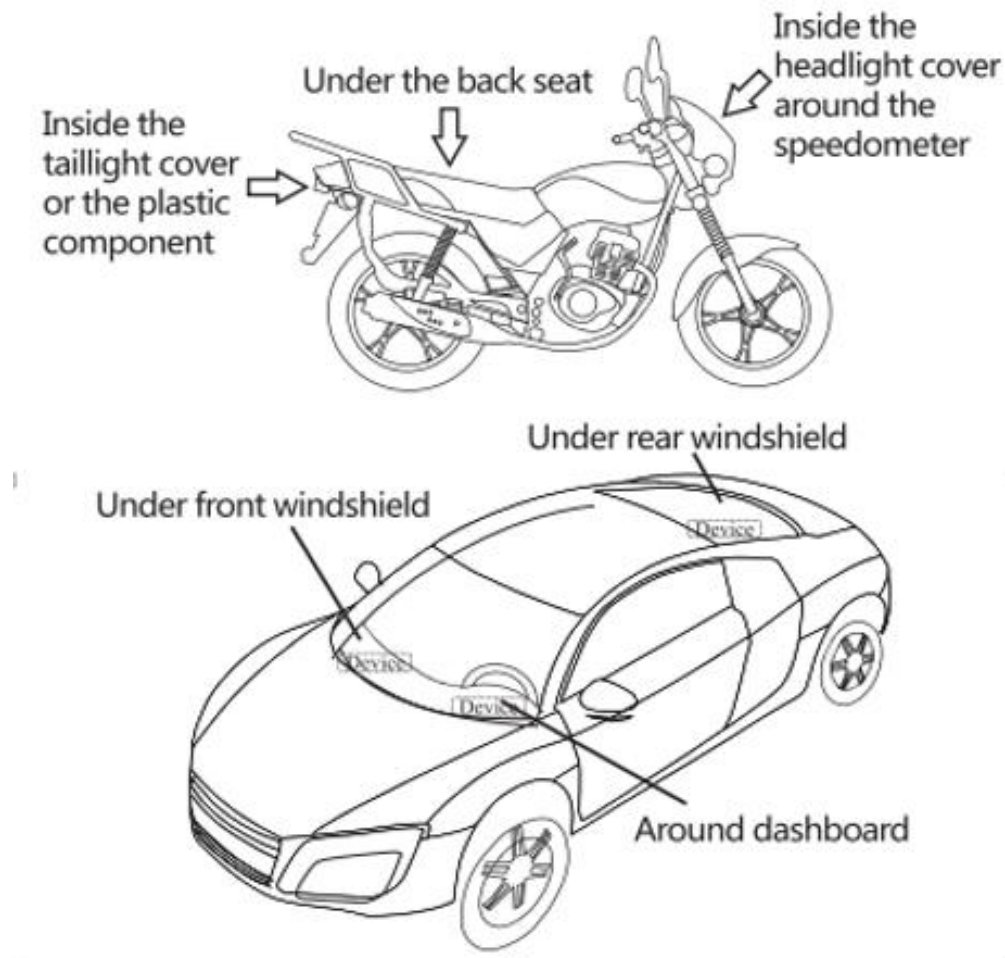
Open the top cover of the device, insert the prepared SIM card into the SIM cardholder, and then confirm that the SIM card button is in place. Please make sure that the SIM card has the GPRS function enabled in advance and know the SIM card number.



### 4.2.2 Main unit power on

After installing the SIM card, turn the battery switch to the ON position. At this time, the red light starts to blink, indicating that the device is power on.

### 4.2.3 Recommended Installation place



### 4.2.4 Parameter setting by SMS

Note: The device is with unique ID number, the factory can preset t IP, port and APN, generally do not need to do parameter setting; if you need to modify the IP, follow the below instructions, make sure the SIMs has SMS functions available:

HC,<T1>,<T2>,<T3>#	<p><b>Set the upload interval in real time tracking mode:</b></p> <p>T1: upload interval in ignition on status, range,5-7200s ,default 30s</p> <p>T2: Upload interval in ignition off status ,range 5-7200s, default 120 s</p> <p>T3: Sleep return interval, range 15-7200s, default 180</p> <p><b>For example:</b></p> <p><b>HC,30,90#</b> Set the upload interval as 30s in ignition on and 90s in ignition off</p> <p><b>HC,30,90,300#</b> Set the upload interval as 30s, 90 s in ignition off and 300s while in <b>sleep mode</b></p>
UTC,TTTT#	<p>Set time zone, unit minutes, default UTC+8:00</p> <p><b>For example:</b></p> <p>UTC,480# Time zone UTC+8:00</p> <p>UTC,330# Time zone UTC+5:30</p> <p>UTC,-480# Time zone UTC-8:00</p> <p>UTC,-210# Time zone UTC-3:30</p>
WY,<A>[,R,M]#	<p>Set towing alarm:</p> <p>A: On and off, 1:On 0:Off Default is off</p> <p>R: Towing radius, Default 500 meters, Range: 100-2000 meters</p> <p>M: Alarm mode, Optional M=0:GPRS,M=1:SMS+GPRS</p> <p><b>Eg:</b> WY,1,100,1# towing alarm on, radius 100 meters notification mode:GPRS+SMS</p>
LOCKACCOFF,A#	<p>Set vehicle lock</p> <p>A=0 Receive lock command, execute immediately</p> <p>A=1 Receive lock command, if ACC is off, execute immediately, if ACC is on, store this command until ACC off</p> <p>A=2 Store the command, lock vehicle from ACC Off to On, if the communication is well, lock vehicle, otherwise wait for next turn</p> <p><b>For example:</b> LOCKACCOFF,0# means execute the lock command immediately after receiving it</p>
APN,apn,user,pswd#	<p>Set APN, User name and password</p> <p><b>For example:</b> APN,CMNET,internet,internet#</p> <p>APN:CMNET</p> <p>Username: internet</p> <p>Password: internet</p>
*22*1#	Restore to factory setting
*22*2#	Lock vehicle

*22*3#	Unlock vehicle
*22*4#	Reboot device
IP,ip or dns,port,type#	IP,119.23.233.52,6000,1# Set the primary server IP:119.23.233.52, port 6000, communication type:TCP IP,www.365qczx.com,6000,0# Set the primary server domain:www.365qczx.com, Port 6000, communication type UDP
IP2,ip or dns,port,type#	IP2,119.23.233.52,6000,1# Set the backend server IP:119.23.233.52,port 6000, communication type is TCP IP2,www.365qczx.com,6000,0# Set the backend server domain:www.365qczx.com, port 6000, communication type: UDP IP2,,0,0# Delete backend server parameter

## LT01 usage requirements

The terminal is strictly forbidden to use according to the operating instructions ,disassemble, collide, charge, soak, over 80 °C, human failure, force majeure damage, etc. may cause short circuit, insufficient working time, battery deformation, liquid leakage, explosion, no warranty and compensation will be provided by KINGWO.



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